

Invariant measure for the cubic wave equation on the unit ball of \mathbb{R}^3

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Abstract

This paper deals with the invariance of a measure on Sobolev spaces of low regularity under the flow of the cubic non linear wave equation on the unit ball of \mathbb{R}^3 under the assumption of spherical symmetry. It presents two aspects, an analytic one which includes the treatment of local properties of the flow, and a probabilistic one, which is mainly related to the global extension of the flow and the invariance of the measure.

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1 Introduction

The goal here is to prove the invariance of the measure ρ constructed in [9], II, under the flow of the cubic non linear wave equation on the unit ball of \mathbb{R}^3 , hence answering the remark 6.3 of the paper by Nicolas Burq and Nikolay Tzvetkov.

The equation studied is :

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$$\begin{cases} \partial_t^2 f - \Delta_{B^3} f + f^3 = 0 & (t, x) \in \mathbb{R} \times B^3 \\ f|_{t=0} = f_0 & \partial_t f|_{t=0} = f_1 \end{cases}, \quad (1)$$

where f is real, radial, B^3 is the unit ball in \mathbb{R}^3 , and Δ_{B^3} is the Laplace-Beltrami operator on B^3 with Dirichlet boundary conditions. Though, it is soon to be changed into its complex form, that is, writing $H = \sqrt{-\Delta_{B^3}}$ and $u = f - iH^{-1}\partial_t f$,

$$\begin{cases} i\partial_t u + Hu + H^{-1}(\operatorname{Re} u)^3 = 0 \\ u|_{t=0} = u_0 = f_0 - iH^{-1}f_1 \end{cases}. \quad (2)$$

In order to define the measure invariant under the flow of (2), a sequence of independent complex centered and normalised (law $\mathcal{N}(0, 1)$) $(g_n)_n$ is introduced, along with the measure μ , which is the image measure of the (well-defined) map from a probability space to the Sobolev space H^σ , $\sigma < \frac{1}{2}$:

$$\varphi(\omega, r) = \sum_{n=1}^{\infty} \frac{g_n}{\pi n} e_n$$

where e_n are the radial eigenfunctions of Δ_{B^3} with eigenvalues $\pi^2 n^2$. It makes μ a sort of limit of gaussian on \mathbb{R}^N when N goes to infinity.

The measure ρ is then defined as :

$$d\rho(u) = e^{-\frac{1}{4}\|u\|_{L^4(B^3)}^4} d\mu(u)$$

absolutely continuous wrt μ . It has been proved that ρ is genuine, the norm $\|\cdot\|_{L^4(B^3)}$ being μ -almost surely finite.

It comes from [9] :

Theorem 1 (Burq, Tzvetkov). *Let $\sigma < \frac{1}{2}$. There exists a set $\Sigma \subseteq H^\sigma$ of full μ or ρ (which is equivalent) measure such that for any initial data u_0 , the flow is globally well-defined and what is more the solution of (2) is unique in $S(t)u_0 + H^s$ where $S(t)$ is the flow of the linear equation $i\partial_t u + Hu = 0$ and s is some real number $s > \frac{1}{2}$.*

Using the ideas of the proof of this theorem and the local property of the solution, the following theorem will be proved.

Theorem 2. *There exists a set $\Pi \subseteq H^\sigma$ of full ρ measure such that the solution of (2) is strongly globally well-defined for any initial data taken in Π and that all measurable set A included in Π satisfies at all time t :*

$$\rho(\psi(t)A) = \rho(A).$$

Before going further, it has to be understood that ρ is built to be invariant under the flow of the non linear wave equation. Actually, by applying a cut-off on the frequency of the Laplace-Beltrami operator with radial symmetry and Dirichlet boundary conditions of the unit ball in \mathbb{R}^3 , the NLW is approached by PDE in finite dimension, susceptible to finite dimension theory, like Cauchy-Lipschitz theorem. Indeed, call E_N the space linearly spanned by N first eigen functions of the radial Laplace-Beltrami operator on the unit ball of \mathbb{R}^3 with Dirichlet boundary conditions, by using projectors on E_N , or, better to say, operators that send H^s into E_N which are more regular

than mere orthogonal projectors, the non linear wave equation can be reduced onto a problem on E_N , which admits a unique maximal condition thanks to Cauchy-Lipschitz theorem that can be proved to be a global one thanks to the existence of a conserved positive energy. The reduction is chosen such that the solutions converges in the space of distributions towards a solution of the non linear wave equation.

Then, finding a measure ρ_N on E_N which is invariant under the flow of this equation relies mostly on the existence of a conserved energy and Liouville theorem. It happens that the sequence ρ_N extended to H^σ converges towards a non trivial measure ρ on H^σ . The measure ρ being a limit of ρ_N , it is expected to be invariant under the flow of NLW.

In previous works, like [6, 3, 4, 11], the strategy applied to prove the invariance of the measure in infinite dimension used the fact that the initial datum was taken in spaces \mathcal{H} such that the orthogonal projectors Π_N on E_N were uniformly bounded, that is to say, there exists C independant from N , such that $\|\Pi_N\|_{\mathcal{H} \rightarrow \mathcal{H}} \leq C$. So the projections $\Pi_N u$ converged toward u in \mathcal{H} uniformly in every compact subset of \mathcal{H} . In these cases, by approaching the the initial data in \mathcal{H} by its projections, the flow with initial data u_0 could be approached by the finite dimensional flow of $\Pi_N u_0$, the convergence being uniform on any compact set of initial data in \mathcal{H} . However, here, the control that ensures the existence of global strong solution in [9] is the norm :

$$\|S(t)u_0\|_{L^p_{t \in [0,2], x \in B^3}},$$

and thus the convergence of $\Pi_N u_0$ in H^σ does not ensure the convergence of this norm applied to $\Pi_N u_0$ and thus not the uniform (regarding the initial data) convergence of finite dimensional solutions towards the global solution.

This problem can be solved though by introducing slightly different “finite” measures and dimensional equations. Instead of entirely reducing the problem to a problem on E_N , only its non linear part will, that is to say, the initial data will be taken in H^σ but the non linear part will be projected on E_N . Therefore, the reduced problem will present two parts : a linear and of infinite dimension one and a finite dimensional though non linear one. Then, the reduced measure ρ_N , instead of being defined on E_N will be defined on all H^σ (and still invariant under the flow). The initial data, thus, will not have to be approached, only the flow will, like in [8]. Unlike in [8] though, considerations on the reversibility of the flow will be confined to the linear treatment. Indeed, the flow of the linear equation is defined on all H^σ which makes it easier to manipulate. The afore-mentioned strategy using the uniform bound of the projectors will be used to prove the invariance of μ under the linear flow. Nevertheless, the flow of the NLW being defined only on a subset Σ of H^s , this subset has to be invariant under the flow if the reversibility of the flow must be used.

To sum up, [9] will provide the topological framework and the local results of existence for the non linear wave equation, [8] the descriptions of the “new” partly finite dimensional measures, [11] a guideline to prove the invariance of the measure μ under the linear flow, [2] the main ideas and properties about random gaussian series, and thanks to all these results, the invariance of ρ shall be proved.

Plan of the paper. The first part is a reminder of the results of [9, 11, 8] rewritten in a slightly different form in order to fit with the framework. The results of [9] are stated at the beginning to display the theorems that compose the starting point. Then, the approximation of the non linear wave equation by finite dimensional problems is detailed. Finally, the first part of the proof of

theorem (2) is given, that is, the construction of the measures μ and ρ and the invariance of μ under the linear flow.

The second part is mainly analytical, it deals with the local properties of the flow. First, the local existence of the flow is derived from [9], then a result of local (in time) uniform (for the initial data) convergence of the approached flow towards the local flow of NLW is given, which leads to a result of local invariance of ρ under the local flow.

The last one is dedicated to the extension of the local solution to a global one when the initial data is taken in Π and then of the extension of the local invariance result to a global one.

2 Existence of solution for the cubic NLW

2.1 Statement of the main results

In [9], Nicolas Burq and Nikolay Tzvetkov have proved that there existed a large subset of H^σ with $\sigma < \frac{1}{2}$ that could be taken as initial data for the 3D-non linear wave equation :

$$(\partial_t^2 - \Delta)u + u^3 = 0 \quad (3)$$

with u a radial function and Δ the Laplace-Beltrami operator on the unit ball of \mathbb{R}^3 .

The first paper shows the existence of local solution using a randomization of the initial data.

The randomization is given by :

Definition 2.1. Let $s \geq \frac{8}{21}$, $f = (f_1, f_2) \in H^s \times H^{s-1}$ and α_n, β_n the sequences defined as :

$$f_1 = \sum_n \alpha_n e_n, \quad f_2 = \sum_n \beta_n e_n$$

with e_n the eigenfunctions of Δ on the unit ball with Dirichlet or Neumann conditions.

Then, let h_n, l_n be sequences of real centered gaussian variables, independant from each other on a probability space Ω, P . Set :

$$f^\omega = (f_1^\omega, f_2^\omega)$$

with

$$f_1^\omega = \sum_n h_n(\omega) \alpha_n e_n, \quad f_2^\omega = \sum_n l_n(\omega) \beta_n e_n.$$

Then, a local solution exists :

Theorem 2.2. Assume $s \geq \frac{8}{21}$ and $f \in H^s \times H^{s-1}$. Set f^ω defined according to the previous randomization. There exists a regularity parameter $\sigma \geq \frac{1}{2}$ such that for almost all $\omega \in \Omega$, there is a time $T_\omega > 0$ such that there is a unique solution to (3) in

$$\cos(\sqrt{-\Delta}t)f_1^\omega + \frac{\sin(\sqrt{-\Delta}t)}{\sqrt{-\Delta}}f_2^\omega + C([-T_\omega, T_\omega], H^\sigma).$$

The second one is dedicated to the global extension of these solutions (with Dirichlet boundary conditions). It states :

Theorem 2.3. Fix $p \in]4, 6[$. Let f_1^ω and f_2^ω be :

$$f_1^\omega = \sum_n \frac{h_n(\omega)}{n\pi} e_n, \quad f_2^\omega = \sum_n l_n(\omega) e_n.$$

Then, for all $s < \frac{1}{2}$ and almost all $\omega \in \Omega$, the problem (3) has a unique global solution in

$$C(\mathbb{R}_t, H^s) \cap L_{loc}^p(\mathbb{R}_t, L^p).$$

To prove this theorem, a cutoff on the frequencies of the Laplace-Beltrami operator is used. The idea is to solve the equation on finite dimensional functional spaces, spanned by the N first eigenfunctions of the Laplacian. Then, by taking limits of the finite dimensional solutions, a subset of Ω of full measure appears into which the norms of the local solutions with initial data of the form $f_0(\omega, \cdot), f_1(\omega, \cdot)$ are controlled as the limits of finite dimensional solutions whose norms are themselves controlled. Therefore, this set of full measure provides a set of functions such that the local solution can be extended. The way these sets of control at finite times are built will inspire the construction of other sets onto which not the flow is strongly globally defined but also onto which the measure that we will define is invariant under this flow.

Before going further, the way the problem is reduced to a finite dimensional one will be described, as the definitions involved shall prove themselves useful for the sequel.

Definition 2.4. Let χ be a C_c^∞ function with support included in $[-1, 1]$ and satisfying

$$\chi \equiv 1$$

on $[-\frac{1}{2}, \frac{1}{2}]$. Then, for all $N \in \mathbb{N}$ we call S_N the operator $\chi(\frac{-\Delta}{N^2})$ that is to say the operator that maps

$$\sum_n c_n e_n$$

to

$$\sum_n c_n \chi\left(\frac{n^2}{N^2}\right) e_n.$$

The set linearly spanned by $\{e_n \mid n \leq N\}$ is now called E_N and Π_N is the orthogonal projection on E_N .

Proposition 2.5. The operators S_N are uniformly continuous from L^p to E_N normed by L^p , that is to say that there exists a constant C independant from N such that for all $f \in L^p$,

$$\|S_N f\|_{L^p} \leq C \|f\|_{L^p}.$$

Also, for all $f \in L^p$, the sequence $(S_N f)_N$ converges towards f in L^p .

The proof of this proposition can be found in [7].

The reduced problem in finite dimension becomes :

$$\begin{cases} i\partial_t u + (-\Delta)^{-1/2} u + S_N((S_N \text{Re} u)^3) = 0 \\ u|_{t=0} = u_0 = f_1 + i(-\Delta)^{-1/2} f_1 \end{cases} \quad (4)$$

This should be explained in the next subsection.

2.2 Approximation of the flow by finite dimensional problems

First, one should see how the equation (4) is derived from the non linear wave equation on the unit ball.

Conserved quantities The initial equation is :

$$\begin{cases} \partial_t^2 f - \Delta_{B^3} f + f^3 = 0 & t, r \in \mathbb{R} \times B^3 \\ f|_{t=0} = f_0 & (\partial_t f)|_{t=0} = f_1 \end{cases} \quad (5)$$

where B^3 is the unit ball of \mathbb{R}^3 and Δ_{B^3} is the Laplace-Beltrami operator on B^3 with Dirichlet boundary conditions.

Now, by setting $H = \sqrt{-\Delta_{B^3}}$, $u_0 = f_0 - iH^{-1}f_1$ and $u = f - iH^{-1}\partial_t f$, u satisfies :

$$\begin{cases} i\partial_t u + Hu + H^{-1}(\text{Re}u)^3 = 0 \\ u|_{t=0} = u_0 \end{cases} \quad (6)$$

Proposition 2.6. *The equation (6) is a Hamiltonian equation with energy :*

$$\mathcal{E}(u) = \frac{1}{2} \int_{B^3} |Hu|^2(r) r^2 dr + \frac{1}{4} \int_{B^3} |\text{Re}u|^4 r^2 dr .$$

The operator S_N is then introduced in order to reduce the problem into an almost finite dimensional one.

Definition 2.7. Set \mathcal{E}_N the quantity :

$$\mathcal{E}_N(u) = \frac{1}{2} \int_{B^3} |Hu|^2 r^2 dr + \frac{1}{4} |S_N \text{Re}u|^4 r^2 dr .$$

This quantity is the hamiltonian of the equation

$$i\partial_t u + Hu + S_N(H^{-1}(S_N \text{Re}u)^3) = 0 .$$

Proposition 2.8. *Set $u_0 \in H^\sigma$ with $\sigma < \frac{1}{2}$ and $S(t) = e^{iHt}$ the flow of the linear equation $i\partial_t u + Hu = 0$ and consider the equation :*

$$\begin{cases} i\partial_t v + Hv + S_N H^{-1}((S_N(S(t)u_0 + v))^3) \\ v|_{t=0} = 0 \end{cases} . \quad (7)$$

There exists a global strong solution called v_N .

Furthermore, $u_N = S(t)u_0 + v_N$ satisfies

$$i\partial_t u_N + Hu_N + S_N(H^{-1}(S_N \text{Re}u_N)^3) = 0$$

with initial data u_0 . The flow of this equation is written $u_N(t) = \psi_N(t)(u_0)$.

The equation (on v) $i\partial_t v + Hv + S_N H^{-1}((S_N(S(t)u_0 + v))^3)$ is on E_N and thus the Cauchy-Lipschitz theorem holds and shows that it admits a local unique solution for any initial condition v_0 , and with u_0 fixed. Then, the quantity $\mathcal{E}_N(\Pi_N S(t)u_0 + v)$ does not depend on time and controls v , which implies that the local solution does not explode and therefore the solution v_N is global.

2.3 Building invariant measures

Now, invariant measures under the flows ψ_N are built. First, call $e_n(r) = \frac{\sin n\pi r}{\sqrt{\pi r}}$ the eigenfunctions of the Laplacian with Dirichlet boundary conditions. Then, let Ω, P be a probability space and $(g_n)_n$ a sequence of independant centered and normalized gaussian variables. Set :

$$\varphi_N(\omega, r) = \sum_{n=1}^N \frac{g_n(\omega)}{n\pi} e_n(r) .$$

The image measure μ_N of φ_N on E_N is absolutely continuous wrt the Lebesgue measure on E_N and :

$$\begin{aligned} d\mu_N\left(\sum_{n=1}^N (a_n + ib_n e_n)\right) &= d_N \prod_{n=1}^N e^{-(n\pi)^2 (a_n^2 + b_n^2)/2} da_n db_n \\ &= d_N e^{-\int_{B^3} |H \sum (a_n + ib_n) e_n|^2} \prod_{n=1}^N da_n db_n \end{aligned}$$

where d_N is a normalization factor.

Thanks to this point of view, it appears that μ_N is invariant under the flow $S(t)$ on E_N . Indeed, by Liouville theorem, the Lebesgue measure on E_N is invariant under the flow and the quantity $\frac{1}{2} \int |Hu|^2$ is invariant under $S(t)$.

Furthermore, the sequence φ_N converges in L^2_Ω, H^σ_r for all $\sigma < \frac{1}{2}$. Denote its limit by φ and call μ the image measure on H^σ of $\omega \mapsto \varphi(\omega, \cdot)$.

Also, considering the measure μ_N^\perp on E_N^\perp (the orthogonal being taken in H^σ) such that

$$\mu = \mu_N \otimes \mu_N^\perp ,$$

it comes that on E_N^\perp, μ_N^\perp is the image measure of

$$\varphi^N : \omega \mapsto \sum_{n=N+1}^{\infty} \frac{g_n(\omega)}{n\pi} e_n .$$

Lemma 2.9. *Let U be an open (for the trace topology of H^σ on E_M^\perp) set of E_M^\perp and call μ_N^M the image measure of*

$$\varphi_N^M : \omega \mapsto \sum_{n=M+1}^N \frac{g_n(\omega)}{n\pi} e_n$$

on E_N^M the space linearly spanned by $\{e_{M+1}, \dots, e_N\}$, such that $\mu_M^\perp = \mu_M^N \otimes \mu_N^\perp$. It comes,

$$\mu_M^\perp(U) \leq \liminf_{N \rightarrow \infty} \mu_N^M(U \cap E_N^M) .$$

In particular, for $M = 0$, this leads to, for all open set U of H^σ ,

$$\mu(U) \leq \liminf_{N \rightarrow \infty} \mu_N(U \cap E_N) .$$

Proof. Let $\sigma < \sigma_1 < \frac{1}{2}$. Let A be the set of Ω , $A = (\varphi^M)^{-1}(U)$ and $A_N = (\varphi_N^M)^{-1}(U \cap E_N^M)$.

If A is empty, then $\mu_M^\perp(U) = 0 = \mu_N^M(U \cap E_N^M)$.

If not, let $\omega \in A$. Since U is an open set, there exists a ball of radius $\epsilon > 0$ such that $\varphi^M(\omega) + B_\epsilon \cap E_M^\perp \subseteq U$. Also,

$$\|\varphi_N^M(\omega) - \varphi^M(\omega)\|_{H^\sigma} \leq N^{\sigma-\sigma_1} \|\varphi(\omega)\|_{H^{\sigma_1}}.$$

The norm $\|\varphi\|_{L_\omega^2, H^{\sigma_1}}$ being finite, for almost all ω , the $\|\varphi(\omega)\|_{H^{\sigma_1}}$ is finite. So, for almost all $\omega \in A$, there exists $N_0 \geq 0$ such that for all $N \geq N_0$, $\varphi_N^M(\omega) \in \varphi^M(\omega) + B_\epsilon \cap E_M^\perp \subseteq U$, as $\varphi_N^M - \varphi^M(\omega) \in E_M^\perp$, that is there exists N_0 such that for all $N \geq N_0$

$$\omega \in A_N \text{ that is to say } \omega \in \liminf A_N.$$

So, $A \subseteq \liminf A_N$ with the possible exception of a negligible set. By Fatou lemma,

$$\mu_M^\perp(U) = P((\varphi^M)^{-1}(U)) = P(A) \leq P(\liminf A_N) \leq \liminf P(A_N) = \liminf \mu_N^M(U \cap E_N) .$$

□

Remark 2.1. For all closed set F of E_M^\perp ,

$$\mu_M^\perp(F) \geq \limsup \mu_N^M(F \cap E_N^M) .$$

Proposition 2.10. The measures μ_M^\perp are invariant under the flow $S(t)|_{E_M^\perp}$. Therefore, with $M = 0$, μ is invariant under $S(t)$.

Proof. Let F be a closed set of E_M^\perp and for all $\epsilon > 0$, call $B_\epsilon^M = B_\epsilon \cap E_M^\perp$ with B_ϵ the open ball of H^σ of radius ϵ . For all $t \in \mathbb{R}$, $S(t)$ is a linear isometry of H^σ and E_M^\perp is invariant under $S(t)$. Thus, as $F + \overline{B_\epsilon^M}$ is a closed set of E_M^\perp , $S(t)F + \overline{B_\epsilon^M} = S(t)(F + \overline{B_\epsilon^M})$ is also closed :

$$\mu_M^\perp(S(t)F + \overline{B_\epsilon^M}) = \mu(S(t)(F + \overline{B_\epsilon^M})) \geq \limsup \mu_N^M(S(t)(F + \overline{B_\epsilon^M}) \cap E_N^M)$$

and as $S(t)A \cap E_N^M = S(t)(A \cap E_N^M)$,

$$\mu_M^\perp(S(t)F + \overline{B_\epsilon^M}) \geq \limsup \mu_N^M(S(t)(F + \overline{B_\epsilon^M}) \cap E_N^M) .$$

Then, μ_N^M is invariant under the flow $S(t)|_{E_N^M}$ for the same reasons as μ_N , so

$$\mu_M^\perp(S(t)F + \overline{B_\epsilon^M}) \geq \limsup \mu_N^M(F + \overline{B_\epsilon^M} \cap E_N^M) \geq \liminf \mu_N^M(F + \overline{B_\epsilon^M} \cap E_N^M)$$

$$\mu_M^\perp(S(t)F + \overline{B_\epsilon^M}) \geq \liminf \mu_N^M(F + B_\epsilon^M \cap E_N^M) .$$

As $F + B_\epsilon^M$ is open in E_M^\perp ,

$$\mu_M^\perp(S(t)F + \overline{B_\epsilon^M}) \geq \mu_M^\perp(F + B_\epsilon^M) \geq \mu_M^\perp(F)$$

and by the dominated convergence theorem when $\epsilon \rightarrow 0$,

$$\mu_M^\perp(S(t)F) \geq \mu_M^\perp(F) .$$

The linear equation is reversible on all E_M^\perp and $S(t)F$ is closed so,

$$\mu_M^\perp(F) = \mu_M^\perp(S(-t)S(t)F) \geq \mu_M^\perp(S(t)F)$$

which gives

$$\mu_M^\perp(F) = \mu_M^\perp(S(t)F)$$

for all time t and all closed set F .

Then, again because $S(t)$ is an isometry on E_M^\perp and thus preserves the topology, this equality is stable under the passage to the complementary and to denombrable union. Therefore, this property is true for all measurable set A and all time t . \square

As the quantity $\frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4$ is μ almost surely finite (see [9]) the measure

$$d\rho_N(u) = e^{-\frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4} d\mu(u)$$

is well-defined on all H^σ .

Proposition 2.11. *The measure ρ_N is invariant under the flow ψ_N globally defined in proposition (2.8) $\psi_N(t) : H^\sigma \rightarrow H^\sigma$.*

Proof. Consider a measurable set A of initial data u_0 . For each u_0 in A , we can write :

$$u_0 = \Pi_N u_0 + \Pi_N^\perp u_0$$

where Π_N^\perp is the orthonormal projector (in H^σ) on E_N^\perp . It suffices to consider A of product type, that is of the type :

$$A = \{u_0 \mid \Pi_N u_0 \in B, \Pi_N^\perp u_0 \in C\}$$

with B and C measurable sets of respectively E_N and E_N^\perp since the topology (and so the measurable sets) of H^σ is the same as the one of the cartesian product $E_N \times E_N^\perp$.

Therefore,

$$\psi_N(t)u_0 = S(t)\Pi_N u_0 + S(t)\Pi_N^\perp u_0 + v(t) = \psi_N|_{E_N}(t)(\Pi_N u_0) + S(t)|_{E_N^\perp} \Pi_N^\perp u_0$$

and thus

$$\psi_N(t)(A) = \psi_N|_{E_N}(t)(B) \times S(t)|_{E_N^\perp}(C) .$$

So, the invariance of ρ_N under ψ_N is reduced to the invariance of μ_N^\perp under $S(t)$ and the invariance of $e^{-\frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4} d\mu_N(u)$ (on E_N) under $\psi_N|_{E_N}$. The first invariance has already been dealt with. For the second one, all $B \subseteq E_N$ measurable satisfies:

$$\begin{aligned} \int_{\psi_N|_{E_N}(t)(B)} e^{-\frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4} d\mu_N(u) &= \int_{\psi_N|_{E_N}(t)(B)} e^{-\frac{1}{2} \int_{B^3} |Hu|^2 - \frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4} dL_N(u) \\ &= \int_{\psi_N|_{E_N}(t)(B)} e^{-\mathcal{E}_N(u)} dL_N(u) \end{aligned}$$

where L_N is the Lebesgue measure on E_N . By Liouville theorem, L_N is invariant under $\psi_N|_{E_N}$, therefore the following change of variable $u = \psi_N|_{E_N}(t)(w)$ holds :

$$\int_{\psi_N|_{E_N}(t)(B)} e^{-\frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4} d\mu_N(u) = \int_B e^{\mathcal{E}_N(\psi_N|_{E_N}(t)(w))} dL_N(w) .$$

Then, remarking that on E_N , $\mathcal{E}_N(\psi_N|_{E_N}(t)(w))$ can be derived over t and is equal to $\mathcal{E}_N(w)$, the measure is invariant and so, ρ_N is invariant under ψ_N . □

Definition 2.12. Let f_N and f be the application on H^σ defined as :

$$f_N(u) = e^{-\frac{1}{4} \int_{B^3} |S_N \text{Re} u|^4} \text{ and } f(u) = e^{-\frac{1}{4} \int_{B^3} |\text{Re} u|^4} .$$

The following statement comes from the analysis of [8].

Proposition 2.13. *The quantity*

$$\frac{1}{4} \int_{B^3} |\text{Re} u|^4$$

is finite for μ -almost all $u \in H^\sigma$.

Besides, f_N converges towards f in L_μ^1 norm.

Therefore, the measure ρ can be introduced as :

Proposition 2.14. *The measure ρ such that :*

$$d\rho(u) = f(u)d\mu(u)$$

is well defined and non trivial. And for all A measurable,

$$\rho(A) = \lim_{N \rightarrow \infty} \rho_N(A) .$$

The proof of the convergence is very similar to the one in the case of the defocusing NLS, as can be found in [8], and then :

$$\rho(A) = \int_A f(u)d\mu(u)$$

$$|\rho(A) - \rho_N(A)| \leq \int_A |f(u) - f_N(u)|d\mu(u) \leq \|f - f_N\|_{L_\omega^1} .$$

The fact that there exists a set of full ρ measure onto which the flow of (6) is well-defined has been proved in [9].

Now, the fact that the measure ρ is invariant under the flow shall be seen.

3 Uniform convergence of the approached flows

3.1 Toolbox

Sobolev embedding For a start, here is the fundamental Sobolev embedding theorem on \mathbb{R}^n .

Theorem 3.1. *Let $n \in \mathbb{N}$ and $s \in \mathbb{R}$. Set $p \in [2, \infty[$ such that $\frac{1}{2} = \frac{1}{p} + \frac{s}{n}$. The functional space $H^s(\mathbb{R}^n)$ is continuously embedded into $L^p(\mathbb{R}^n)$. That is to say, there exists a constant $C(s)$ such that for all $f \in H^s(\mathbb{R}^n)$,*

$$\|f\|_{L^p} \leq C\|f\|_{H^s} .$$

Remark 3.1. *By considering f radial and with compact support on B^3 the unit ball in dimension 3, as a particular case of the precedent theorem for all f radial and with compact support on B^3 and in $H^s(\mathbb{R}^3)$, that is to say for all $f \in \mathcal{H}^s$, it comes :*

$$\|f\|_{L^p(B^3)} \leq C\|f\|_{H^s(B^3)}$$

as long as $\frac{1}{2} = \frac{1}{p} + \frac{s}{3}$.

The proof of Sobolev embedding thorem can be found in [1].

Deep into the local existence of solution for the cubic NLW The goal here is to show that on certain sets, the flows ψ_N converges uniformly towards ψ . So, first, deterministic Strichartz estimates and needed properties of the flow are described.

Definition 3.2. Let $p > 2$, q such that $\frac{1}{p} + \frac{1}{q} = \frac{1}{2}$, $T > 0$ and $s = \frac{2}{p}$. Call

$$X_T^s = C^0([-T, T], H^s(B^3)) \cap L^p((-T, T), L^q(B^3))$$

where B^3 is the unit ball in \mathbb{R}^3 and

$$Y_T^s = L^1([-T, T], H^{-s}(B^3)) + L^{p'}((-T, T), L^{q'}(B^3))$$

its dual where p' and q' are the conjugate numbers of p and q .

Proposition 3.3. *Let $p \in]4, 6[$ and $s = \frac{3}{2} - \frac{4}{p}$. There exists a constant C such that for all $T \in]0, 1]$ and all f ,*

$$\|f\|_{L^p([0, T], L^p(B^3))} \leq C\|f\|_{X_T^s} \text{ and } \|f\|_{Y_T^s} \leq C\|f\|_{L^{p'}([-T, T] \times B^3)} .$$

The proof comes from a particular case of interpolation between the two functional spaces described in the definition of X_T^s .

Thanks to a combination of Sobolev embedding theorem and Strichartz inequality (see [10] for further details), the following property holds :

Proposition 3.4. *Let $p \in]4, 6[$ and s defined as $s = \frac{3}{2} - \frac{4}{p}$, there exists $C \leq 0$ such that for all $T \in [0, 1]$ and all $f \in H^s$:*

$$\|S(t)f\|_{L^p([-T, T] \times B^3)} \leq C\|f\|_{H^s} .$$

Proposition 3.5. *Let $p \in]4, 6[$, $p_1 \in]4, 6[$ such that $p_1 > p$, $s = \frac{3}{2} - \frac{4}{p}$ and $s_1 = \frac{3}{2} - \frac{4}{p_1} > s$. There exists C such that for all $T \in]0, 1]$ and all f ,*

$$\int_0^t S(t-u)H^{-1}f(u)du\|_{X_T^s} \leq C\|f\|_{Y_T^{1-s}}$$

$$\|(1-S_N) \int_0^t H^{-1}S(t-u)f(u)du\|_{X_T^s} \leq CN^{s-s_1}\|f\|_{Y_T^{1-s_1}} .$$

The proof can be found in [9]. The last crucial result needed from this article is the local existence theorem, and its implication regarding the X_T^s norms of the function $v(t) = \psi(t)u_0 - S(t)u_0$ where $\psi(t)$ would be defined as the flow of

$$i\partial_t u + Hu + H^{-1}(\text{Re}u)^3 = 0$$

that is to say v is the solution of

$$\begin{cases} i\partial_t v + Hv + H^{-1}((\text{Re}(S(t)u_0 + v(t)))^3) = 0 \\ v|_{t=0} = 0 \end{cases} . \quad (8)$$

Theorem 3.6. *Choose a real number $p \in]4, 6[$ and define s as $s = \frac{3}{2} - \frac{4}{p}$. There exists $C > 0$, $c > 0$, $\gamma = 1 - \frac{4}{p}$ such that for any arbitrary large number A , there exists a time of existence $\tau \in]0, 1]$ depending on A as $\tau = c(1+A)^{-\gamma}$ such that for all initial data u_0 satisfying $\|S(t)u_0\|_{L_{t,x}^p \in [0,2] \times B^3} \leq A$, there exist unique solutions of the equations (7) and (8), v_N and v , belonging to X_τ^s and satisfying :*

$$\|v\|_{X_\tau^s}, \|v_N\|_{X_\tau^s} \leq CA .$$

Also, as $S(t)$ is 2 periodic (the eigenvalues of the Laplacian on B^3 with Dirichlet boundary conditions are of the form $(n\pi)^2$, $n \in \mathbb{N}^*$) and thanks to the proposition (3.4), there exists another constant C' such that for each $t \in [-\tau, \tau]$:

$$\|S(t')(u(t))\|_{L_{t',x}^p}, \|S(t')(u_N(t))\|_{L_{t',x}^p} \leq \|S(2t')u_0\|_{L_{t',x}^p} + \|S(t')v(t)\|_{L_{t',x}^p} \leq C'A$$

and if $u_0 \in H^\sigma$, the solutions satisfies :

$$\|u(t)\|_{H^\sigma}, \|u_N(t)\|_{H^\sigma} \leq C'\|u_0\|_{H^\sigma}$$

with $u(t) = S(t)u_0 + v$ and $u_N(t) = S(t)u_0 + v_N$.

Remarks on sets' measurements The local results of existence will provide local properties of uniform convergence of the sequence of flows ψ_N toward the flow ψ and then induce properties on the invariance of the flow that will remain local. In order to extend those next to appear local properties into a global invariance of the flow, we will have to control the quantity denoted as A in the previous theorem. But this control has to satisfy certain properties, such as the set that describes the initial data that lead to a controlled solution must be of full measure.

To this purpose, consider the following proposition.

Proposition 3.7. *Let $\sigma < \frac{1}{2}$, let $p \in]4, 6[$, let $D \geq 0$ and consider the sets :*

$$B(D)^c = \{u_0 \in H^\sigma \mid \|S(t)u_0\|_{L^p_{t,x}} > D\}$$

and

$$E(D)^c = \{u_0 \in H^\sigma \mid \|u_0\|_{H^\sigma} > D\}.$$

There exists $c > 0$ independant from D such that :

$$\rho(B(D)^c), \rho_N(B(D)^c) \leq \mu(B(D)^c) \leq e^{-cD^2}$$

and

$$\rho(E(D)^c), \rho_N(E(D)^c) \leq \mu(E(D)^c) \leq e^{-cD^2}.$$

The proof depends on the lemma 3.3 that can be found in [8].

Remark 3.2. *It will appear that the time $\tau_1 < \tau$ such that there is local convergence on $X_{\tau_1}^s$ depends on D . It will then be necessary to prove that τ_1 is big enough to control $u(t)$ at some finite times t_k with $k \in \mathbb{Z}$ cover all times, and still have a set of initial data of full ρ measure.*

3.2 Local uniform convergence

We now want to prove that the flows ψ and ψ_N are such that $\psi(t)u_0 - \psi_N(t)u_0$ converges in $X_{\tau_1}^s$ for some τ_1 uniformly in u_0 .

Lemma 3.8. *Let $\sigma \in]0, \frac{1}{2}[$, $p \in]4, 6[$ and s defined as $s = \frac{3}{2} - \frac{4}{p}$. Fix $D \geq 0$ and consider $A(D)$ the set*

$$A(D) = \{u_0 \in H^\sigma \mid \|S(t)u_0\|_{L^p} \leq D \text{ and } \|u_0\|_{H^\sigma} \leq D\}.$$

There exists $c_1 > 0$ and $\gamma_1 > 0$ such that by fixing $\tau_1 = \min(c_1(1+D)^{-\gamma_1}, \tau)$, where τ is the time provided by the theorem (3.6) for all $\epsilon > 0$, there exists $N_0 \geq 0$ such that for all $u_0 \in A(D)$ and all $N \geq N_0$,

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{X_{\tau_1}^s} < \epsilon,$$

that is to say that $\psi_N(t)u_0$ converges uniformly in $u_0 \in A(D)$ in $X_{\tau_1}^s$.

Proof. Let $u_0 \in A(D)$ and v and v_N be such that

$$\psi(t)u_0 = S(t)u_0 + v(t) \text{ and } \psi_N(t)u_0 = S(t)u_0 + v_N(t).$$

The functions v and v_N are both in X_τ^s so the norm

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{X_{\tau_1}^s} = \|v - v_N\|_{X_{\tau_1}^s}$$

is finite for all $\tau_1 \leq \tau$.

For all $t \leq \tau$:

$$v(t) - v_N(t) = \int_0^t S(t-s)H^{-1} \left((\text{Re}\psi(s)u_0)^3 - S_N((S_N \text{Re}\psi_N(s)u_0)^3) \right) ds$$

that is to say $v - v_N = I_N + II_N$ with

$$I_N = (1 - S_N) \int_0^t S(t-s) H^{-1} \left((\operatorname{Re} \psi(s) u_0)^3 \right) ds$$

and

$$II_N = \int_0^t S(t-s) S_N H^{-1} \left((\operatorname{Re} \psi(s) u_0)^3 - (\operatorname{Re} S_N \psi_N(s) u_0)^3 \right) ds .$$

Thanks to proposition (3.5), for $T \leq \tau$ and $s_1 > s$

$$\|I_N\|_{X_T^s} \leq C N^{s-s_1} \|(\operatorname{Re} \psi u_0)^3\|_{Y_T^{1-s_1}}$$

with C independant from D , T , and N . Let p_1 be such that $1 - s_1 = \frac{3}{2} - \frac{4}{p_1}$. The condition $s_1 > s$ is equivalent to $p_1 < \frac{2p}{p-2}$. Hence :

$$\|I_N\|_{X_T^s} \leq C N^{s-s_1} \|(\operatorname{Re} \psi u_0)^3\|_{L_{t,x}^{p'_1}}$$

$$\|I_N\|_{X_T^s} \leq C N^{s-s_1} \|(\operatorname{Re} \psi u_0)\|_{L^{3p'_1}}^3 .$$

To majore this norm, the condition $3p'_1 \leq p$ is wanted. This condition is equivalent to $p_1 \geq \frac{p}{p-3}$, which means p_1 has to be chosen in the interval $[\frac{p}{p-3}, \frac{2p}{p-2}]$. But since $p > 4$, $\frac{p}{p-3} < \frac{2p}{p-2}$, and so, such a choice is possible, and in particular, by choosing $p_1 = \frac{p}{p-3}$, or $3p'_1 = p$, it comes :

$$\|I_N\|_{X_T^s} \leq C N^{s-s_1} (\|S(t)u_0\|_{L^p} + \|v\|_{L^p})^3$$

$$\|I_N\|_{X_T^s} \leq C N^{s-s_1} (\|S(t)u_0\|_{L^p} + \|v\|_{X_T^s})^3$$

and thanks to theorem (3.6), $\|v\|_{X_T^s} \leq CD$ with C independant from D and T as long as $T \leq \tau$ so

$$\|I_N\|_{X_T^s} \leq C N^{s-s_1} D^3 .$$

Therefore, for all $\epsilon > 0$, there exists N_0 such that for all $u_0 \in A(D)$, all $T \leq \tau$ and all $N \geq N_0$,

$$\|I_N\|_{X_T^s} \leq \epsilon .$$

Once more, thanks to (3.5),

$$\|II_N\|_{X_T^s} \leq \|((\operatorname{Re} \psi(s) u_0)^3 - (\operatorname{Re} S_N \psi_N(s) u_0)^3)\|_{Y_T^{1-s}}$$

and with p_2 such that $1 - s = \frac{3}{2} - \frac{4}{p_2}$ that is $p_2 = \frac{2p}{p-2}$,

$$\|II_N\|_{X_T^s} \leq \|((\operatorname{Re} \psi(s) u_0)^3 - (\operatorname{Re} S_N \psi_N(s) u_0)^3)\|_{L^{p'_2}} .$$

Since

$$|(\operatorname{Re} \psi(s) u_0)^3 - (\operatorname{Re} S_N \psi_N(s) u_0)^3| \leq \frac{3}{2} |\operatorname{Re} \psi(s) u_0 - \operatorname{Re} S_N \psi_N(s) u_0| \left((\operatorname{Re} \psi(s) u_0)^2 + (\operatorname{Re} S_N \psi_N(s) u_0)^2 \right) ,$$

by Hölder inequality with $\frac{1}{p'_2} = \frac{1}{3p'_2} + \frac{2}{3p'_2}$,

$$\|II_N\|_{X_T^s} \leq \|\operatorname{Re}\psi(s)u_0 - \operatorname{Re}S_N\psi_N(s)u_0\|_{L^{3p'_2}} \|(\operatorname{Re}\psi(s)u_0)^2 + (\operatorname{Re}S_N\psi_N(s)u_0)^2\|_{L^{3p'_2/2}}$$

$$\leq \|\operatorname{Re}\psi(s)u_0 - \operatorname{Re}S_N\psi_N(s)u_0\|_{L^{3p'_2}} \left(\|(\operatorname{Re}\psi(s)u_0)^2\|_{L^{3p'_2/2}} + \|(\operatorname{Re}S_N\psi_N(s)u_0)^2\|_{L^{3p'_2/2}} \right)$$

As $3p'_2 = \frac{6p}{p+2} < p$ and

$$\|(\operatorname{Re}\psi(s)u_0)^2\|_{L^{3p'_2/2}} = \|\operatorname{Re}\psi(s)u_0\|_{L^{3p'_2}}^2 \leq T^{2\gamma_2} \|\psi(s)u_0\|_{L^p}^2$$

with $\gamma_2 = \frac{p-4}{6p}$, it comes that :

$$\|II_N\|_{X_T^s} \leq CD^2 T^{2\gamma_2} \|\operatorname{Re}\psi(s)u_0 - \operatorname{Re}S_N\psi_N(s)u_0\|_{L^{3p'_2}}$$

with C independent from D and T as long as $T \leq \tau$.

Now, the quantity $\|\operatorname{Re}\psi(s)u_0 - \operatorname{Re}S_N\psi_N(s)u_0\|_{L^{3p'_2}} \leq \alpha_N + \beta_N$ remains to be considered, with $\alpha_N = \|(1 - S_N)\psi(s)u_0\|$ and $\beta_N = \|S_N(\psi(s)u_0 - \psi_N(s)u_0)\|$.

By the same convex inequalities as precedently,

$$\beta_N \leq CT^{\gamma_2} \|\psi(s)u_0 - \psi_N(s)u_0\|_{L^p} \leq CT^{\gamma_2} \|\psi(s)u_0 - \psi_N(s)u_0\|_{X_T^s}.$$

Choose $2 < p_3 < \frac{3}{3/2-\sigma} \in]2, 3[$ and call $\sigma_3 = 3\left(\frac{1}{2} - \frac{1}{p_3}\right) < \sigma$. As $p_3 < 3 < 3p'_2 < p$ so, there exists $\theta \in]0, 1[$ such that $\frac{1}{3p'_2} = \frac{\theta}{p_3} + \frac{1-\theta}{p}$, thus

$$\alpha_N \leq \|(1 - S_N)\psi(s)u_0\|_{L^{p_3}}^\theta \|(1 - S_N)\psi(s)u_0\|_{L^p}^{1-\theta}$$

$$\|(1 - S_N)\psi(s)u_0\|_{L^p} \leq C(\|S(t)u_0\|_{L^p} + \|v\|_{X_T^s}) \leq CD$$

and by Sobolev embedding theorem :

$$\|(1 - S_N)\psi(s)u_0\|_{L^{p_3}} \leq \|(1 - S_N)\psi(s)u_0\|_{L_t^{p_3} H_x^{\sigma_3}}$$

Now, for all s ,

$$\|(1 - S_N)\psi(s)u_0\|_{H^{\sigma_3}} \leq CN^{\sigma_3-\sigma} \|\psi(s)u_0\|_{H^\sigma} \leq CDN^{\sigma_3-\sigma}$$

and so

$$\alpha_N \leq CN^{\theta(\sigma_3-\sigma)} D^\theta D^{1-\theta} = CN^{\theta(\sigma_3-\sigma)} D.$$

Therefore, for all $\epsilon > 0$, there exists N_0 such that for all $u_0 \in A(D)$, all $T \leq \tau$, and all $N \geq N_0$,

$$\alpha_N \leq \epsilon.$$

Now, let us sum up these inequalities.

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{X_T^s} \leq I_N + CD^2 T^{2\gamma_2} (\alpha_N + \beta_N) \leq I_N + C\alpha_N + CD^2 T^{3\gamma_2} \|\psi(t)u_0 - \psi_N(t)u_0\|_{X_T^s}.$$

Set $\gamma_1 = \max(\gamma, \frac{2}{3\gamma_2})$ and $\tau_1 = \min(\tau, C^{-1/(3\gamma_2)}(1+D)^{-\gamma_1})$, such that $CD^2\tau_1^{3\gamma_2} < CD^2\tau_1^{2/\gamma_1} < 1$, hence

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{X_{\tau_1}^s} \leq C(I_N + \alpha_N)$$

so for all $\epsilon > 0$ there exists N_0 such that for all $u_0 \in A(D)$ and all $N \geq N_0$

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{X_{\tau_1}^s} \leq \epsilon .$$

□

Remark 3.3. Note that the construction of γ_1 ensures that $\gamma_1 \geq \gamma$ but that τ_1 is still a power of D .

3.3 Local invariance

Let us show that the measure is invariant under the flow locally in time. That is, as long as the sequence $\psi_N(t)u_0$ converges uniformly on some sets, it will appear that $\rho(\psi(t)A) \geq \rho(A)$. This is the first step in order to reach a global invariance result for the measure.

Lemma 3.9. Let $\sigma \in]0, \frac{1}{2}[$, $p \in]4, 6[$, $s = \frac{3}{2} - \frac{4}{p}$, and $D > 0$. Set $A(D)$ the set described in (3.8), $\tau = c(1+D)^{-\gamma}$ the local existence time coming from theorem (3.6) and $\tau_1 = \min(\tau, c_1(1+D)^{-\gamma_1})$ the local time of uniform convergence, all three depending only on D and p . Then, for all $A \subseteq A(D)$ measurable, and all $t \in [-\tau_1, \tau_1]$, the set $\psi(t)A$ is measurable and :

$$\rho(\psi(t)A) = \rho(A) .$$

Proof. First, for all A measurable, $\psi(t)A$ is also measurable thanks to the local continuity of the flow. Assume now that A is a closed set of H^σ included in $A(D)$ and set $\epsilon > 0$. By lemma (3.8), there exists N_0 such that for all $u_0 \in A(D)$ and all $N \geq N_0$

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{X_{\tau_1}^s} \leq \epsilon .$$

But by definition, $\|\cdot\|_{X_{\tau_1}^s} \geq \|\cdot\|_{C^0([-\tau_1, \tau_1], H^s(B^3))}$. So for all $t \in [-\tau_1, \tau_1]$,

$$\|\psi(t)u_0 - \psi_N(t)u_0\|_{H^s} \leq \epsilon .$$

Let B_ϵ be the ball in H^s of center 0 and radius ϵ , as $A \subseteq A(D)$, for all $N \geq N_0$, and all $t \in [-\tau_1, \tau_1]$,

$$\psi_N(t)(A) \subseteq \psi(t)(A) + B_\epsilon$$

therefore

$$\rho_N(\psi_N(t)(A)) \leq \rho_N(\psi(t)(A) + B_\epsilon) .$$

Then, since the measure ρ_N is invariant under the flow ψ_N , as it is stated in proposition (2.11),

$$\rho_N(\psi_N(t)A) = \rho_N(A)$$

and thus

$$\rho_N(A) \leq \rho_N(\psi(t)A + B_\epsilon) .$$

Then, using the fact that (proposition (2.13)), for all μ measurable set B ,

$$\rho(B) = \lim_{N \rightarrow \infty} \rho_N(B),$$

and as the property $\rho_N(A) \leq \rho_N(\psi(t)A + B_\epsilon)$ is true for all $N \geq N_0$, by taking the limit :

$$\rho(A) \leq \rho(\psi(t)A + B_\epsilon)$$

and then by making ϵ tend toward 0, thanks to the dominated convergence theorem,

$$\rho(A) \leq \rho(\psi(t)A)$$

and that for all $t \in [-\tau_1, \tau_1]$. Indeed, $\psi(-t) = \psi(t)^{-1}$ is continuous in H^σ , so $\psi(t)A$ is closed in H^σ .

For the reverse inequality, use the fact that indeed, $\psi(t)A \subseteq \psi_N(t)A + B_\epsilon$ for all $u_0 \in A(D)$ and $n \geq N_0$. It is also true that the ball \widetilde{B}_ϵ of radius ϵ in H^σ contains B_ϵ as $\sigma < \frac{1}{2} < s$, so :

$$\psi(t)A \subseteq \psi_N(t)A + \widetilde{B}_\epsilon.$$

Then, the fact that the equation is reversible, and so $\psi_N(t)^{-1} = \psi_N(-t)$ is used. Also, thanks to the continuity of the local flow on H^σ , there exists a constant C depending on the time t but not on ϵ or N such that :

$$\psi_N(-t)(\psi_N(t)A + \widetilde{B}_\epsilon) \subseteq A + \widetilde{B}_{C\epsilon}$$

so

$$\psi(t)A \subseteq \psi_N(t)A + \widetilde{B}_\epsilon \subseteq \psi_N(t)(A + \widetilde{B}_{C\epsilon})$$

and

$$\rho_N(\psi(t)A) \leq \rho_N(\psi_N(t)(A + \widetilde{B}_{C\epsilon})) = \rho_N(A + \widetilde{B}_{C\epsilon})$$

thanks to the invariance of ρ_N under ψ_N .

By passing to the limit $N \geq N_0 \rightarrow \infty$,

$$\rho(\psi(t)A) \leq \rho(A + \widetilde{B}_{C\epsilon})$$

and then $\epsilon \rightarrow 0$,

$$\rho(\psi(t)A) \leq \rho(A)$$

so for all closed set A of H^σ included in $A(D)$,

$$\rho(\psi(t)A) = \rho(A).$$

Then, remark that $A(D)$ is a closed set of H^σ , so

$$\rho(\psi(t)A(D)) = \rho(A(D))$$

and thus the property of invariance under the flow passes to the complementary and the denumerable unions. It holds on every measurable set. \square

4 Measure invariance

4.1 Building sets of full measure with global existence

We now need to build a set of full ρ measure such that in this set not only the local invariance result holds but also can be extended to a global one, that is to say that in this set the flow must be globally well defined.

Definition 4.1. Let

$$D_{i,j} = (i + j^{1/\gamma_1})^{1/2}$$

with $i, j \in \mathbb{N}$ and set $T_{i,j} = \sum_{l=1}^j \tau_l(D_{i,l})$. Let

$$\Pi_{N,i} = \{u_0 \mid \forall j \in \mathbb{N}, \psi_N(\pm T_{i,j}) \in A(D_{i,j+1})\}$$

and

$$\Pi_i = \limsup_{N \rightarrow \infty} \Pi_{N,i}$$

and finally

$$\Pi = \bigcup_{i \in \mathbb{N}} \Pi_i .$$

Proposition 4.2. *The set Π is of full ρ measure.*

Proof. Let us compute the measure of the complementary set of Π .

First, as

$$\Pi_{N,i} = \bigcap_{j \in \mathbb{N}} \psi_N(\pm T_{i,j})^{-1}(A(D_{i,j+1})) ,$$

$$\rho(\Pi_{N,i}^c) \leq \|f - f_N\|_{L_\mu^1} + \rho_N(\Pi_{N,i}^c)$$

and

$$\rho_N(\Pi_{N,i}^c) \leq \sum_{j=0}^{\infty} \rho_N(\psi_N(\pm T_{i,j})^{-1}(A(D_{i,j+1}))^c) .$$

Then, using that $(\psi_N(\pm T_{i,j})^{-1}(A(D_{i,j+1}))^c)^c = \psi_N(\pm T_{i,j})^{-1}(A(D_{i,j})^c)$, it becomes clear that the ρ_N measures of these sets are equal and as ρ_N is invariant under the flow ψ_N :

$$\rho_N(\Pi_{N,i}^c) \leq 2 \sum_j \rho_N(A(D_{i,j})^c) \leq 2 \sum_j \mu(A(D_{i,j})^c)$$

But, $A(D)^c = B(D)^c \cup E(D)^c$ with B and E the sets defined in (3.7) so

$$\mu(A(D)^c) \leq \mu(B(D)^c) + \mu(E(D)^c) \leq 2e^{-cD^2}$$

so

$$\rho_N(\Pi_{N,i}) \leq C \sum_j e^{-cD_{i,j}^2}$$

and so

$$\rho(\Pi_{N,i}^c) \leq C e^{-ci} \sum_j e^{-cj^{1/\gamma_1}} \leq C e^{-ci}$$

as $e^{-cj^{1/\gamma_1}}$ is the general term of a convergent series.

Therefore :

$$\rho(\Pi_i^c) = \rho(\liminf \Pi_{N,i}^c) \leq \liminf \rho(\Pi_{N,i}^c) = e^{-cD^2 i} + \liminf \|f - f_N\|_{L_\mu^1} = C e^{-ci}$$

and then

$$\rho(\Pi^c) = \rho\left(\bigcap_i \Pi_i^c\right) \leq \lim \rho(\Pi_i^c) = 0$$

that is to say that Π is of full measure. \square

Lemma 4.3. *Let $u_0 \in \Pi_i$, the flow $\psi(t)u_0$ is strongly globally defined and for all $j \in \mathbb{N}$ and $\psi(\pm T_{i,j})u_0$ belongs to $A(D_{i,j+1})$.*

Proof. As $u_0 \in \Pi_i = \limsup \Pi_{N,i}$, there exists a sequence $N_k \rightarrow \infty$ such that for all k , $u_0 \in \Pi_{N_k,i}$, which is equivalent to $\psi_{N_k}(\pm T_{i,j})u_0 \in A(D_{i,j})$ for all $j \in \mathbb{N}$.

Then, by recurrence over j , it can be proved that $\psi(t)u_0$ is defined on $[-T_{i,j}, T_{i,j}]$ and that $\psi(\pm T_{i,j})u_0 - \psi_{N_k}(\pm T_{i,j})u_0$ converges toward 0 in \mathcal{H}^s when $k \rightarrow \infty$.

For $j = 0$, $T_{i,0} = 0$ and so $u_0 = \psi_{N_k}(\pm T_{i,0})u_0 \in A(D_{i,1})$ and $\psi(T_{i,0})u_0 - \psi_{N_k}(T_{i,0})u_0 = 0$ converges toward 0 in H^s .

Suppose that at rank j , $\psi(t)u_0$ strongly exists on $[-T_{i,j}, T_{i,j}]$ and $\psi(\pm T_{i,j})(u_0) - \psi_{N_k}(\pm T_{i,j})(u_0)$ converges toward 0 in H^s . Let us show that the property holds at rank $j + 1$. As

$$\|\psi(\pm T_{i,j})(u_0) - \psi_{N_k}(\pm T_{i,j})(u_0)\|_{H^\sigma} \leq \|\psi(\pm T_{i,j})(u_0) - \psi_{N_k}(\pm T_{i,j})(u_0)\|_{H^s}$$

and

$$\|S(t)(\psi(\pm T_{i,j})(u_0) - \psi_{N_k}(\pm T_{i,j})(u_0))\|_{L_{t,x}^p} \leq \|\psi(\pm T_{i,j})(u_0) - \psi_{N_k}(\pm T_{i,j})(u_0)\|_{H^s}$$

and for all k ,

$$\|\psi_{N_k}(\pm T_{i,j})(u_0)\|_{H^\sigma} \leq D_{i,j+1}$$

and

$$\|S(t)(\psi_{N_k}(\pm T_{i,j})(u_0))\|_{L_{t,x}^p} \leq D_{i,j+1},$$

by taking the limits when $k \rightarrow \infty$, it comes that $u_\pm := \psi(\pm T_{i,j})u_0 \in A(D_{i,j+1})$.

So, thanks to theorem (3.6) $\psi(t)u_\pm$ is strongly defined on $[-\tau_1, \tau_1] \subseteq [-\tau, \tau]$ and thanks to lemma (3.8),

$$\psi(t)u_\pm - \psi_{N_k}(t)u_\pm$$

converges toward 0 in $X_{\tau_1(D_{i,j+1})}^s$. In particular,

$$\psi(\pm\tau_1(D_{i,j+1})u_{\pm} - \psi_{N_k}(\pm\tau_1(D_{i,j+1}))u_{\pm})$$

converges toward 0 in H^s .

Then, as

$$\psi(\pm T_{i,j+1})u_0 - \psi_{N_k}(\pm T_{i,j+1})u_0 = \psi(\pm\tau_1(D_{i,j+1})u_{\pm} - \psi_{N_k}(\pm\tau_1(D_{i,j+1}))u_{\pm} +$$

$$\psi_{N_k}(\pm\tau_1(D_{i,j+1}))u_{\pm} - \psi_{N_k}(\pm\tau_1(D_{i,j+1}))(\psi_{N_k}(\pm T_{i,j})u_0$$

and since $v \mapsto \psi_N(\pm\tau_1(D_{i,j+1}))v$ is uniformly in N continuous from $H^s \cap A(D_{i,j+1})$ to H^s , it implies that

$$\psi_{N_k}(\pm\tau_1(D_{i,j+1}))u_{\pm} - \psi_{N_k}(\pm\tau_1(D_{i,j+1}))(\psi_{N_k}(\pm T_{i,j})u_0$$

also converges toward 0 in H^s . Therefore,

$$\psi(\pm T_{i,j+1})u_0 - \psi_{N_k}(\pm T_{i,j+1})u_0$$

converges toward 0 in H^s and as it has precedently been seen, it implies that $\psi(\pm T_{i,j+1}) \in A(D_{i,j+2})$. \square

4.2 Global invariance

Now, a first result of global invariance can be proved.

Proposition 4.4. *Let A be a measurable set included in Π_i . Then for all $t \in \mathbb{R}$, we have*

$$\rho(\psi(t)(A)) = \rho(A) .$$

Proof. In order to prove such a fact, it is required that the sequence $T_{i,j}$ where i is fixed diverges.

Indeed,

$$\tau_1(D_{i,j}) = \min(\tau(D_{i,j}, c_1(1 + D_{i,j})^{-\gamma_1}) = \min(c(1 + D_{i,j})^{-\gamma}, c_1(1 + D_{i,j})^{-\gamma_1})$$

and $D_{i,j} = \sqrt{i + j^{1/\gamma_1}}$ diverges. Therefore, as $\gamma_1 \geq \gamma$, above a certain rank $\tau_1(D_{i,j}) = c_2(1 + D_{i,j})^{-\gamma_1}$ with $c_2 = c_1$ if $\gamma < \gamma_1$ or $c_2 = \min(c, c_1)$ otherwise.

So, $\tau_1(D_{i,j})$ behaves like $j^{-1/2}$ when $j \rightarrow \infty$ and so the sequence $T_{i,j}$ diverges.

Let $t \in \mathbb{R}$, there exists j such that $t \in [T_{i,j}, T_{i,j+1}]$ if $t \geq 0$ or $t \in [-T_{i,j+1}, -T_{i,j}]$. Let us show by recurrence over j that for all $t \in [T_{i,j}, T_{i,j+1}] \cup [-T_{i,j+1}, -T_{i,j}]$,

$$\rho(\psi(t)A) = \rho(A)$$

For $j = 0$, we have $T_{i,0} = 0$, $T_{i,1} = \tau_1(D_{i,1})$ and $A = \psi(T_{i,0})(A) \subseteq \psi(T_{i,0})(\Pi_i) \subseteq A(D_{i,1})$ thanks to lemma (4.3). So, the local invariance lemma (3.9) holds : for all $t \in [-\tau_1(D_{i,1}), \tau_1(D_{i,1})]$,

$$\rho(\psi(t)(A)) = \rho(A) .$$

For $j-1 \Rightarrow j$, $\psi(\pm T_{i,j})(A) \subseteq \psi(T_{i,j})(\Pi_i) \subseteq A(D_{i,j+1})$ (lemma (4.3)). So, by using lemma (3.9), for all $t \in [0, \tau_1(D_{i,j+1})]$,

$$\rho\left(\psi(\pm t)\left(\psi(\pm T_{i,j})(A)\right)\right) = \rho\left(\psi(\pm T_{i,j})(A)\right) .$$

Then, by using the recurrence hypothesis,

$$\rho\left(\psi(\pm T_{i,j})(A)\right) = \rho(A) .$$

And so, for all

$$\begin{aligned} t &\in [T_{i,j}, T_{i,j} + \tau_1(D_{i,j+1})] \cup [-T_{i,j} - \tau_1(D_{i,j+1}), -T_{i,j}] \\ &= [T_{i,j}, T_{i,j+1}] \cup [-T_{i,j+1}, -T_{i,j}] , \end{aligned}$$

it comes

$$\rho(\psi(t)(A)) = \rho(\psi(t)(A)) .$$

□

Theorem 4.5. *For all ρ measurable set included in Π , we have :*

$$\rho(\psi(t)(A)) = \rho(A) .$$

Proof. As $\Pi = \bigcup_i \Pi_i$, and $A \subseteq \Pi$, A can be written :

$$A = \bigsqcup_{i \in \mathbb{N}} A_i$$

with $A_i \subseteq \Pi_i$, and the A_i disjoint. So,

$$\psi(t)(A) = \bigsqcup_{i \in \mathbb{N}} \psi(t)A_i$$

since the flow is strongly defined in Π .

$$\rho(\psi(t)A) = \sum_{i \in \mathbb{N}} \rho(\psi(t)A_i) = \sum_{i \in \mathbb{N}} \rho(A_i) = \rho\left(\bigsqcup_{i \in \mathbb{N}} A_i\right) = \rho(A) .$$

□

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